





Introduction

- In this topic, we will
 - Review the seven tools we will use to find algorithms for numerical algorithms
 - Look at the upcoming four topics





Weighted averages

- To begin, the first tool is weighted averages:
 - If $\overline{w_1 + w_2 + \dots + w_n} = 1$ are weights, then $w_1 x_1 + w_2 x_2 + \dots + w_n x_n$

is a weighted average of the *n x*-values

If all the weights are greater-than-or-equal to zero,
 we call it a convex combination, and

$$\min\{x_1, x_2, \dots, x_n\} \le w_1 x_1 + w_2 x_2 + \dots + w_n x_n \le \max\{x_1, x_2, \dots, x_n\}$$







Iteration

- The second tool is iteration:
 - It is possible to devise algorithms that can be implemented as a function F so that if x_0 approximates a value, then, under certain conditions, $F(x_0)$ is a better approximation
 - Such an algorithm can be iterated
- Specifically, if we are solving x = f(x) where f is an algebraic expression in x, we can proceed as follows:
 - Start with an initial approximation x_0
 - Let $x_{k+1} \leftarrow f(x_k)$
 - If this sequence converges, it converges to a solution of x = f(x)
- We saw that it is necessary to limit the number of iterations:
 - If there are too many iterations, we should halt
 - If $|x_{k+1} x_k|$ is sufficiently small, assume x_{k+1} is close enough







Linear algebra

- The third tool is linear algebra:
 - Solving a system of linear equations $A\mathbf{u} = \mathbf{v}$ is the only such system that can be generally solved
 - We will approximate non-linear equations with linear ones
 - When applying Gaussian elimination, it is necessary to use partial pivoting to avoid adding a large multiple of one row onto another
 - It is also possible to rewrite $A\mathbf{u} = \mathbf{v}$ in the form

$$\mathbf{u} = A_{\text{diag}}^{-1} \left(\mathbf{v} - A_{\text{off}} \mathbf{u} \right)$$

which can then be iterated

- This will converge if *A* is strictly diagonally dominant
- We discussed the condition number of a matrix
 - Any error in *A*, **v** or numeric error in solving is potentially magnified by up to the condition number







Interpolation

- The fourth tool is interpolation:
 - Given n points, we can always find a unique polynomial of degree n-1 that passes though all n points
 - This requires the *x* values are all unique
 - This requires the generation of a Vandermonde matrix
 - The condition number of the Vandermonde matrix is smaller if:
 - The x-values are closer to the origin
 - The *x*-values are equally spaced
 - The number of points n is kept small
 - The former can be achieved by shifting the *x*-values towards the origin by subtracting off their average







Taylor series

- The fifth tool is Taylor series:
 - For an appropriately differentiable function,
 the Taylor series gives both the approximation and the error
 - We will write Taylor series in the form:

$$f(x+h) = f(x) + f^{(1)}(x)h + \frac{1}{2}f^{(2)}(\xi)h^2$$

- An n^{th} -order Taylor series approximates f with a polynomial of degree n together with an error term multiplied by h^{n+1}
 - We will say the error is $O(h^{n+1})$
- We will use Taylor series both to analyze the errors in our approximations, the rates of converges of various iterative algorithms, and motivate solutions other analytic problems





Bracketing

- The sixth tool is bracketing:
 - If nothing else, if we can constrain a solution to lie on an interval [a, b], it may be possible to devise an algorithm to reduce the interval on which the solution exists
 - We may, therefore, be able to reduce the range of values over which a solution exists
 - We will call this *bracketing* the solution,
 but this is not common in the literature







Intermediate-value theorem

- The seventh tool is the intermediate-value theorem:
 - If f is a continues function defined on the interval [a, b], then
 - The function f takes on all values between f(a) and f(b) for some value of x on that interval
 - The function f also takes on all values between the extreme points the function achieves on the interval [a, b]
 - This will be used to determine the error of many of our algorithms







Looking ahead

- We have now described the tools we will use
 - In the next four topics, we will apply these tools to solve problems associated with
 - Approximate values of algebraic and analytic expressions
 - Approximating solutions to algebraic equations and systems of algebraic equations
 - This includes both linear equations and non-linear equations
 - Approximating solutions to analytic equations and systems of analytic equations
 - This includes initial- and boundary-value problems for both ordinary and partial differential equations
 - Approximating solutions to optimization problems







Summary

- Following this topic, you now
 - Reviewed the seven tools we will use
 - Described the next four topics in the course





References

[1] https://en.wikipedia.org/wiki/Numerical_analysis







Acknowledgments

None so far.







Colophon

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